

Column Generation Basics

Ed Klotz, Ph.D., Mathematical Optimization Specialist, Gurobi Optimization, New Trier East class of 1978 Greg Glockner, Ph.D., Technical Fellow, Gurobi Optimization, New Trier East class of 1988 May, 2024

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Question 1

Consider the LP min $c^T x$ s.t. $A_1 x = b$ $x \ge 0$

Suppose A_1 has 10000 constraints and 50000 variables. At any simplex method iteration, how many variables are basic?

- < 10000
- 10000
- More than 10000 but less than 50000
- 50000



Question 2

Consider the LP min $c^T x$ s.t. $A_2 x = b$ $x \ge 0$

Suppose A_2 has 10000 constraints and 10³⁰ variables. At any simplex method iteration, how many variables are basic?

- < 10000
- 10000
- More than 10000 but less than 10^{30}
- 10³⁰



Column Generation, what's that all about?



It didn't make it on Broadway, but...

• From Dantzig, Linear Programming and Extensions, 1963

to use one might say about Sub's new plan, it cer. tainly has gone easy on the use of tankers; in fact, none are used. But look what has happened to costs—they have nearly doubled! I just can't tell Sub that he can have only 9 tankers and let him find his own least-cost solution; I tried that the last time there was a tanker shortage, and costs soared. Somehow I wish I had sent Sub to that six-week operations research course, instead of the ten-day one. It would probably have been a lot cheaper in the long run. Note: At this point, Staff has decided to call in his economist friend, DALKS: According to good economic theory, what you should do is to tell Sub that there may be an extra premium charge for the use of tankers. This will teach Sub to keep the costs down and at the same time not use tankers excessively, because they are now part of the charges in the total bill. STAFF (Enthusiastic and not above a bit of subterfuge if it gets results): Let's do just that. (F.M. is crestfallen; theory is theory, but putting it into practice is another matter.) DALKS: Let's go a little more slowly. It is not always easy to calculate what the prices should be on scarce commedition It

```
Anyway, a more included in the source of the
                 handle price problems when there are breakpoints due to dis-
                 continuity in the derivatives of the underlying production functions.
                  But this is beside the point. The article suggests that we should
                  But this is the average of the two plans (he moves to the blackboard)
                                                     P_1\lambda_1 + P_2\lambda_2 = \begin{bmatrix} 53\\18 \end{bmatrix}\lambda_1 + \begin{bmatrix} 95\\0 \end{bmatrix}\lambda_2
                     like this:
                    where \lambda_1 + \lambda_2 = 1, and, of course, 0 \le \lambda_1 \le 1. For example, we
                      could try \lambda_1 = \frac{1}{2}, \lambda_2 = \frac{1}{2}. Say, this gives
                                                                                              \frac{1}{2}(53+95)=74
                                                                                               \frac{1}{2}(18 + 0) = 9
                         which is a lot cheaper than 95 and happens to use up the available
STAFF: That's splendid, simply splendid! But how do we know that we can
                            average Sub's proposals in this way? How will Sub know what to
                            do? I don't want to get into the details of Sub's shipping schedule,
```



We need to expand into a new line of business.

Act 1

All of our high tech business lines are losing money. We need to move into something more low tech and boring that is quietly profitable



Act 1

I've decided we are going to expand into clothing, lumber,
steel and paper production. In order to do that, we'll
need to be able to solve cutting stock problems.

What is the cutting stock problem?

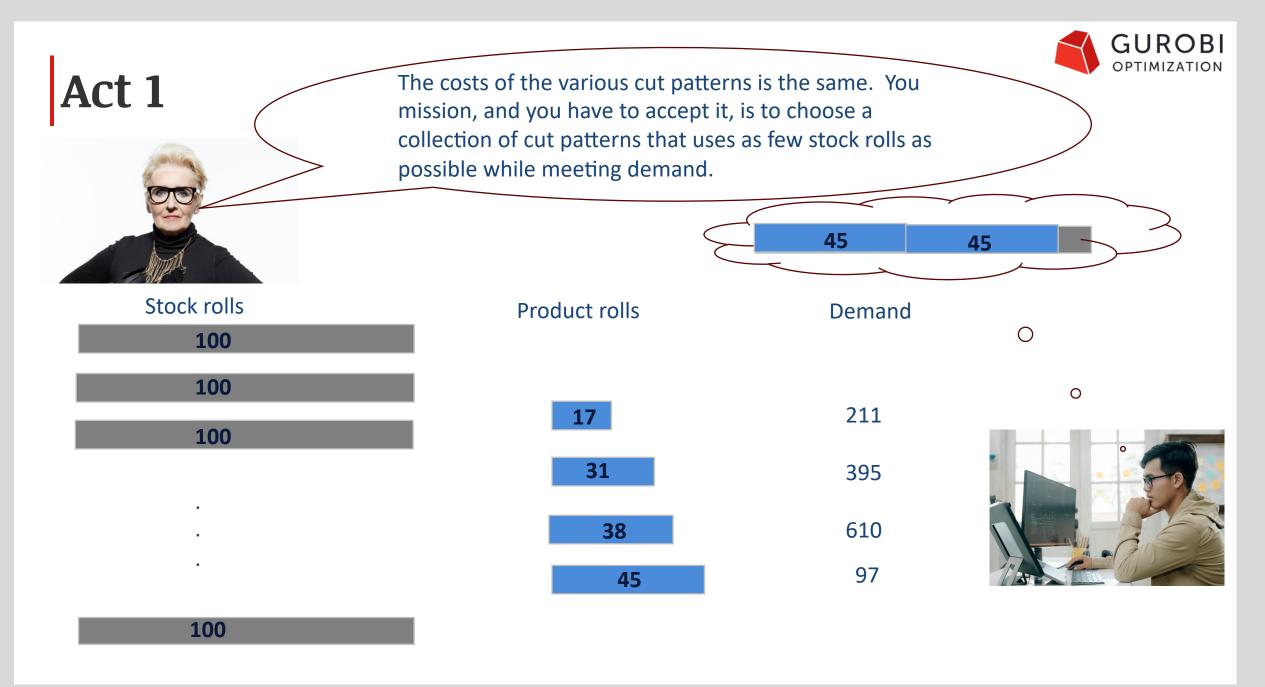


The one dimensional cutting stock problem involves Act 1 cutting rectangles of smaller widths out of generic rectangles (the "stock") with the same standard width. Here's an example. Stock rolls Product rolls Demand 100 100 211 17 100 31 395 . 38 610 97 45

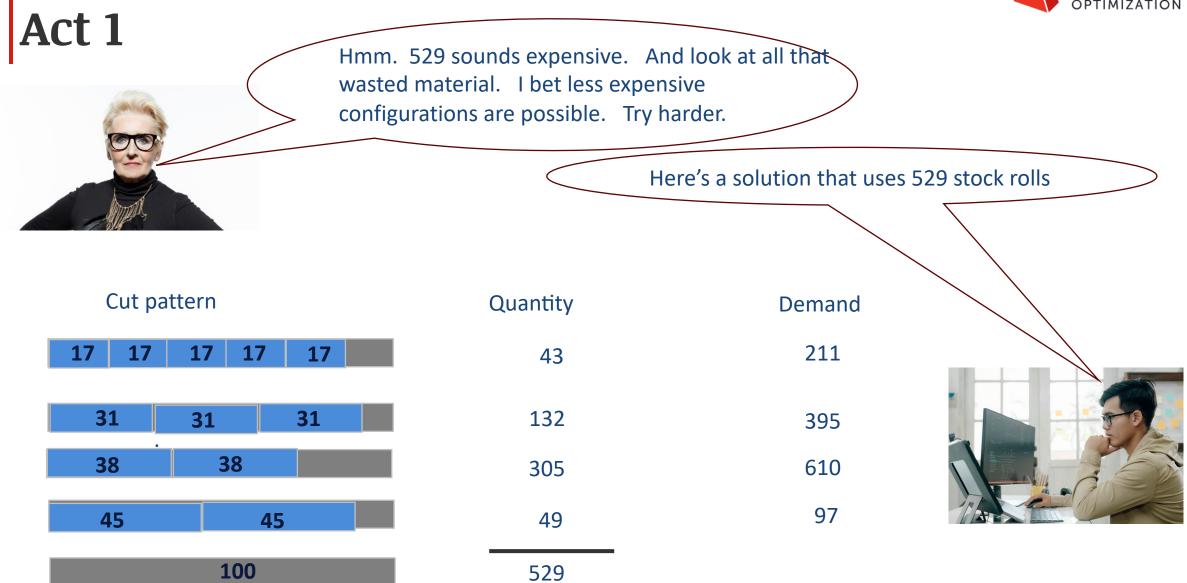
100

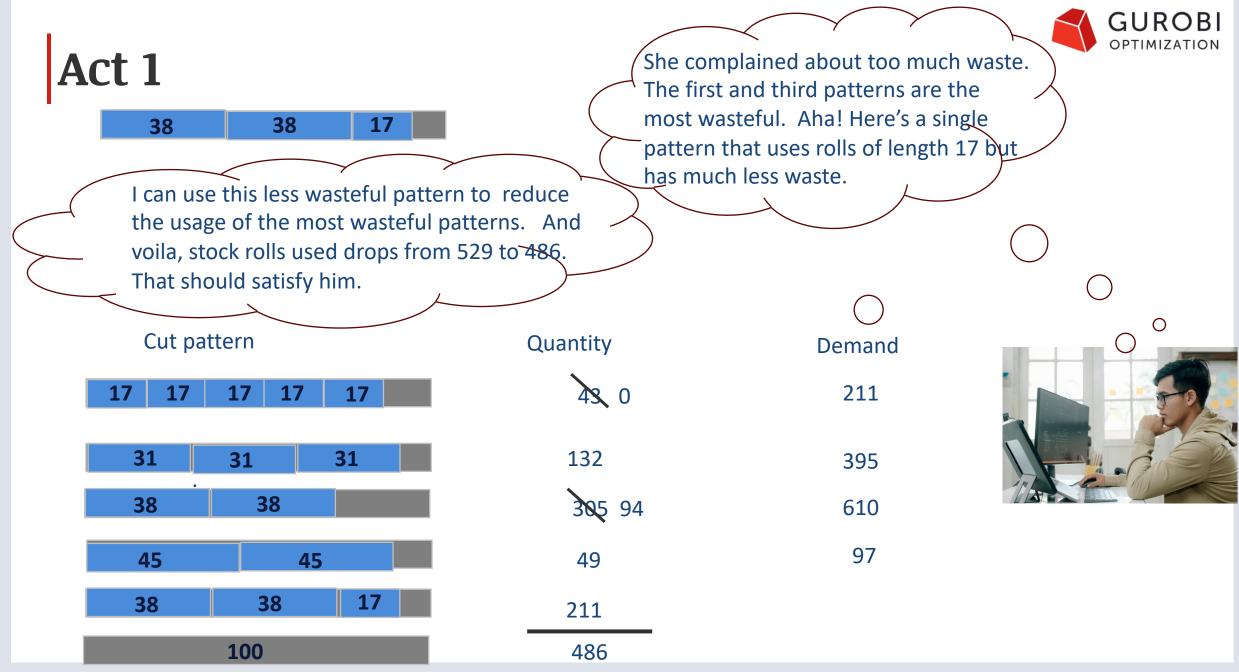
Modified problem from Linear Programming by Chvatal

GUROBI



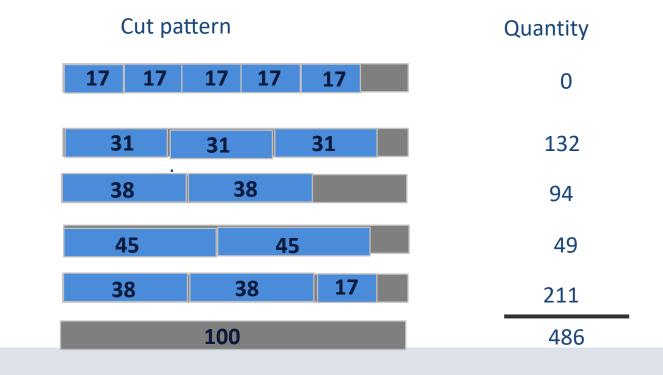








Accounting says our profit margins will still be small with that manufacturing cost. And we're still using that third pattern 94 times despite all the waste.



Act 1

•			
		A A	
The second			K

Demand

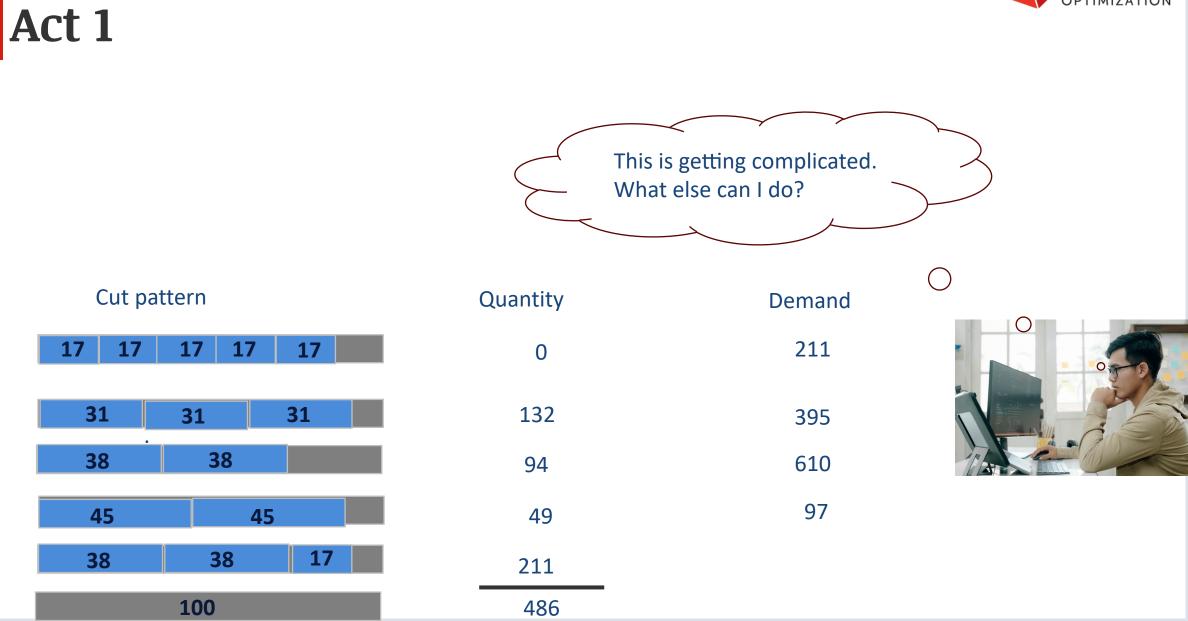
211

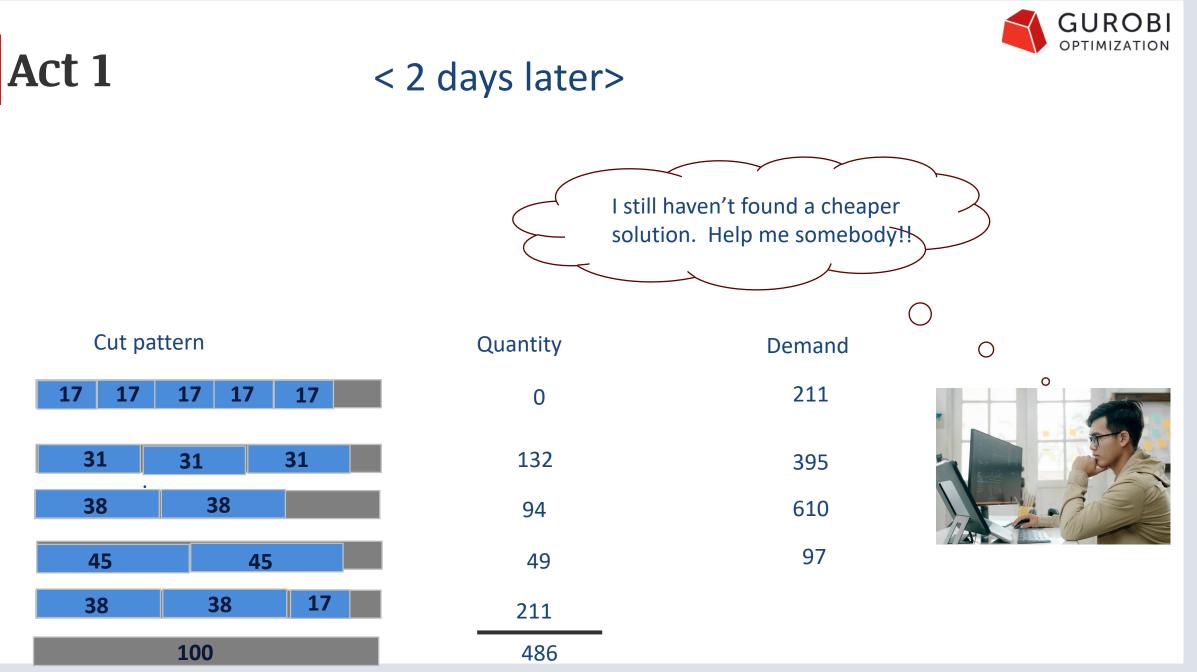
395

610

97







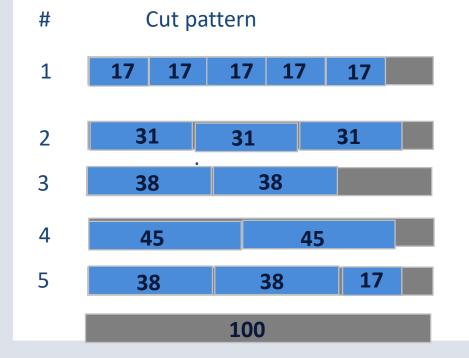


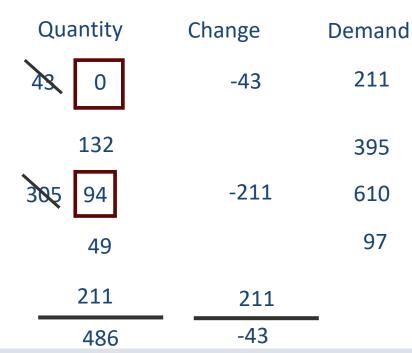


Act 2

Think about what you did to reduce the cost with pattern 5. While you viewed it as reducing waste, you could also view it as reducing cost. You added 211 rolls cut with pattern 5, but you eliminated 43 rolls cut with pattern 1 and 211 rolls with pattern 3, for a savings of 43 = 529 - 486



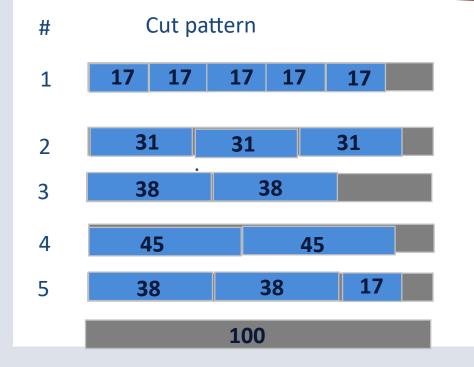








Act 2 That worked, but it then was harder to find another pattern that yielded more savings. What you need to do is use an algorithm to efficiently search for additional cut patterns that yield more savings. That's where column generation can help you. It will find new patterns where the reduction in stock rolls it enables exceeds the increased use of the new pattern.



Quantity	Change	Demand
0	-43	211
132		395
94	-211	610
49		97
211	211	_
486	-43	





Act 2

So how do you know about column generation?

It's taught in the second week of onboarding at our waste management company. We need to figure out the most cost efficient route to meet our customer pickups. Column generation is very helpful for vehicle routing problems, either pickup like we do or delivery like all sorts of companies do.

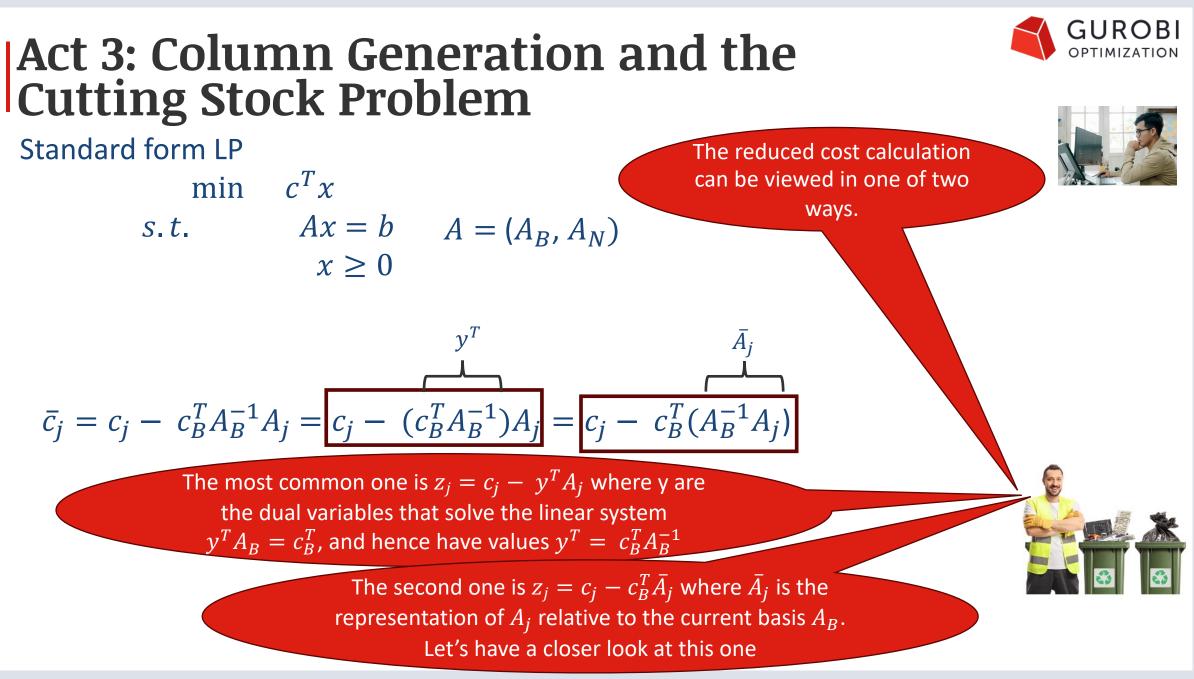


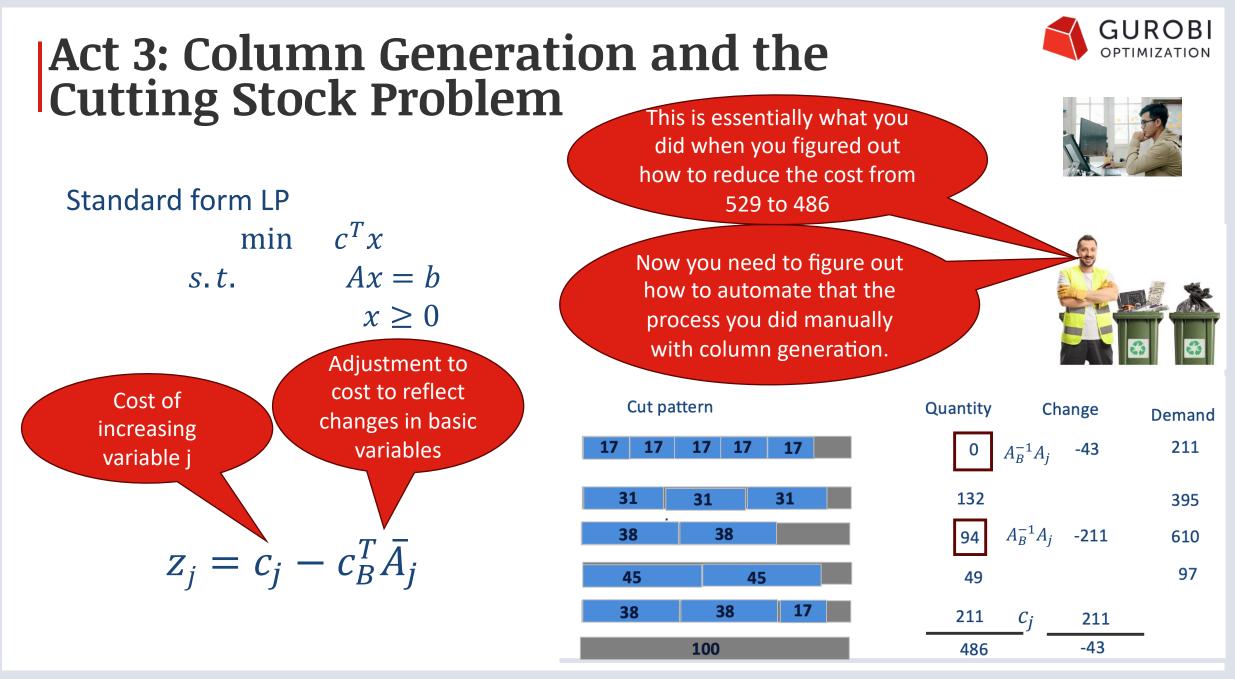


Intermission

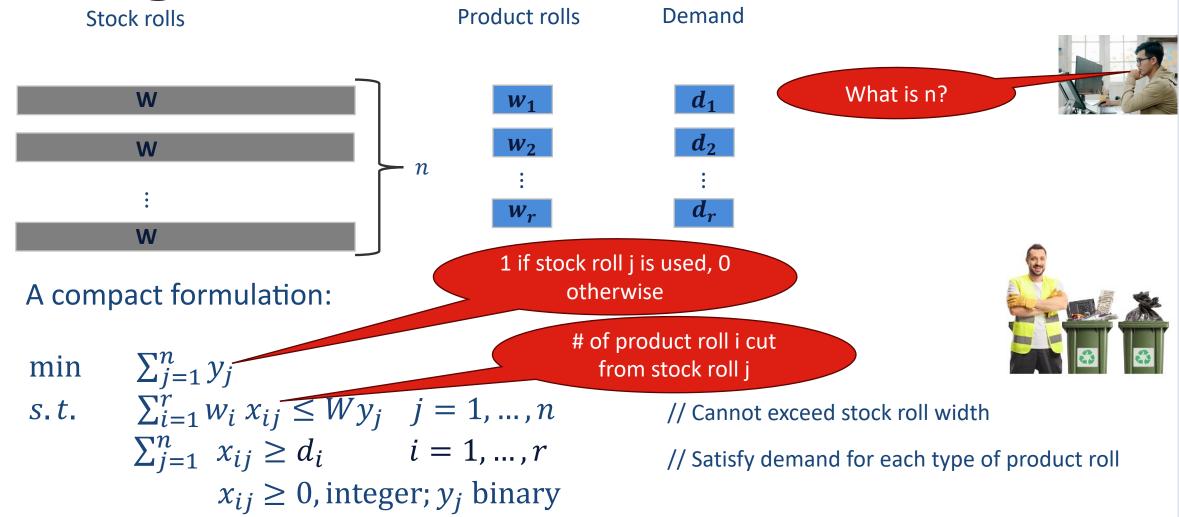
What are the takeaways from Acts 1 and 2?

- There was no mention of mathematical programming, linear algebra, or other optimization terminology
- An iterative procedure emerged involving a dialog between the Boss and the Software Engineer. Each person passed information to the other that helped refine the best solution
- Even a very small cutting stock problem is not that easy to solve.



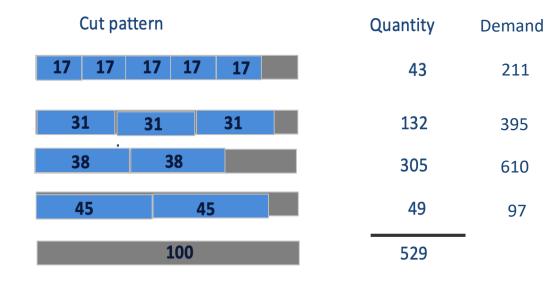








 $\begin{array}{ll} \min & \sum_{j=1}^{n} y_j \\ s.t. & \sum_{i=1}^{r} w_i \, x_{ij} \leq W y_j \quad j = 1, \dots, n \\ & \sum_{j=1}^{n} \, x_{ij} \geq d_i \qquad i = 1, \dots, r \\ & x_{ij} \geq 0, \text{ integer; } y_j \text{ binary} \end{array}$



What is n? Ah, I see. I just need to look for solutions better than that obvious one that use fewer stock rolls. So n = $\sum_{i=1}^{r} ceil(d_i/floor(W/w_i))$

Think about that simple first solution you proposed. You just cut a single type of product roll from each stock roll until you met demand.



 $\begin{array}{ll} \min & \sum_{j=1}^{n} y_j \\ s.t. & \sum_{i=1}^{r} w_i \, x_{ij} \leq W y_j \quad j=1,\ldots,n \\ & \sum_{j=1}^{n} \, x_{ij} \geq d_i \qquad i=1,\ldots,r \\ & x_{ij} \geq 0, \text{ integer; } y_j \text{ binary} \end{array}$

We have this compact formulation. Why do we need column generation?

What do you mean weakness of the formulation?

This formulation will work fine for small cutting stock problems like the one we examined. But for larger problems with more different types of product rolls, solving this version of the model can become problematic due to the inherent weakness of the formulation.





Weakness of a MIP formulation

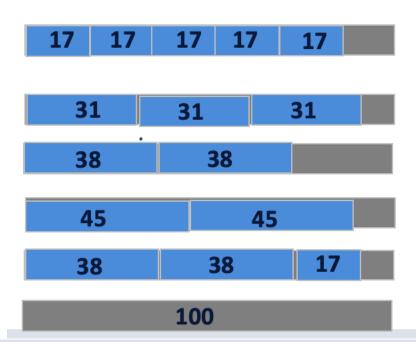
- Discussed in previous tech talk "Converting Weak to Strong MIP Formulations", parts I and II
 - <u>https://www.gurobi.com/events/tech-talk-chat-converting-weak-to-strong-mip-formulations/</u>
 - <u>https://www.gurobi.com/events/tech-talk-chat-converting-weak-to-strong-mip-formulations-part-ii/</u>
 - Upcoming book chapter: Klotz, E. and Oberdieck, R. (2024 forthcoming). Converting Weak to Strong MIP Formulations: A Practitioner's Guide. In: Hamid, F. (ed.) Optimization Essentials: Theory, Tools, and Applications. International Series in Operations Research & Management Science, vol 353. Springer, Singapore. <u>https://doi.org/10.1007/978-981-99-5491-9_4</u>
- Consider the level of disconnect between the physical systems modeled by the MIP formulation and its LP relaxation



 $\begin{array}{ll} \min & \sum_{j=1}^{n} y_j \\ s.t. & \sum_{i=1}^{r} w_i \, x_{ij} \leq W y_j \quad j=1,\ldots,n \\ & \sum_{j=1}^{n} \, x_{ij} \geq d_i \qquad i=1,\ldots,r \end{array}$

 $x_{ij} \ge 0$, integer; y_j binary

Cut pattern



What do you mean weakness of the formulation?

We've seen how the system associated with the MIP formulation works. Individual cut patterns can result in wasted material

That no longer holds in the LP relaxation. We can reassemble wasted material into product rolls at no cost. Let's see how that works



Act 3: Column Generation and the Cutting Stock Problem min $\sum_{j=1}^{n} y_j$

s.t. $\sum_{i=1}^{r} w_i x_{ij} \le W y_j$ j = 1, ..., n $\sum_{i=1}^{n} x_{ii} \ge d_i \qquad i = 1, \dots, r$

 $x_{ij} \ge 0$, integer; y_i binary

17	17	17	17	17	15
17	17	17	17	17	15
17	17	17	17	17	15

15

Ah, so the fractional rolls still count towards meeting demand in the LP relaxation model.

Algebraically, consider cutting only product roll i=1, namely rolls of length 17; this results in waste of length 15 in each associated stock roll. Consider 4 such identical rolls.

The LP relaxation solution will set $x_{1i} = 5^{15}/_{17}$ and $y_i = 1$ for j = 11, ... 4, resulting in a total of $\sum_{i=1}^{4} x_{ii}$ =23 product rolls and waste of 4*15 – 3*17 = 9

The MIP solution generates 20 product rolls of length 17, with a total waste of 4*15 = 60



Act 3: Column Generation and the Cutting Stock Problem min $\sum_{j=1}^{n} y_j$

17

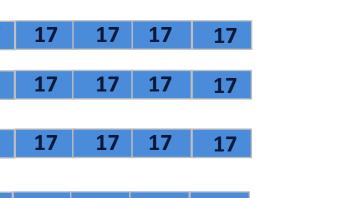
17

s.t. $\sum_{i=1}^{r} w_i x_{ij} \le W y_j$ j = 1, ..., n $\sum_{i=1}^{n} x_{ii} \ge d_i$ i = 1, ..., r

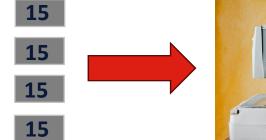
 $x_{ij} \ge 0$, integer; y_i binary

Visually, relaxing integrality introduces a new zero cost process that stitches together waste material shorter than any product roll into a legitimate product roll

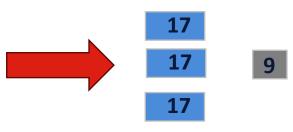




17









Act 3: Column Generation and the Cutting Stock Problem $\min_{\substack{\sum_{i=1}^{n} y_i}}$

17

17

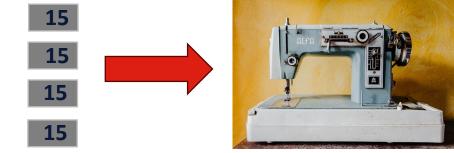
17

9

10

s.t. $\sum_{i=1}^{r} w_i x_{ij} \le W y_j \quad j = 1, ..., n$ $\sum_{j=1}^{n} x_{ij} \ge d_i \qquad i = 1, ..., r$ $x_{ij} \ge 0, \text{ integer; } y_j \text{ binary}$



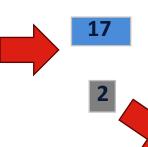


45

45

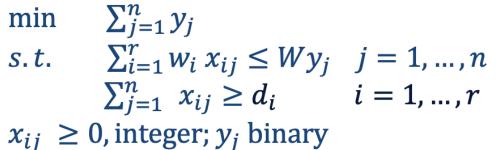
The waste from the preceding 4 stock roll cuts can be combined at no cost with waste from other cuts to produce additional product rolls



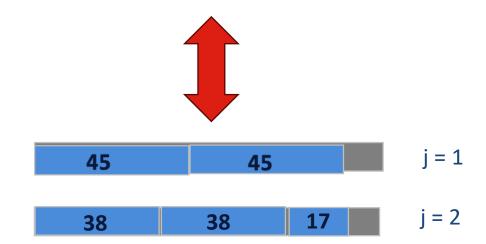










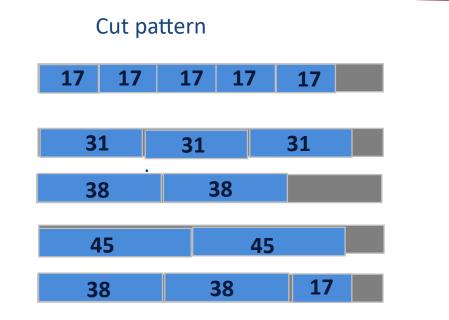


Symmetry is another source of weakness in this formulation. The indexing of the rolls is arbitrary and interchangeable



I think I see how to formulate the model to use column generation. I'll implicitly consider all feasible cut patterns and encode the number of product rolls in each pattern. I can't explicitly enumerate all possible encodings, but I can enumerate enough to create a restricted master problem, then let the subproblem efficiently find other good encoded

cut patterns



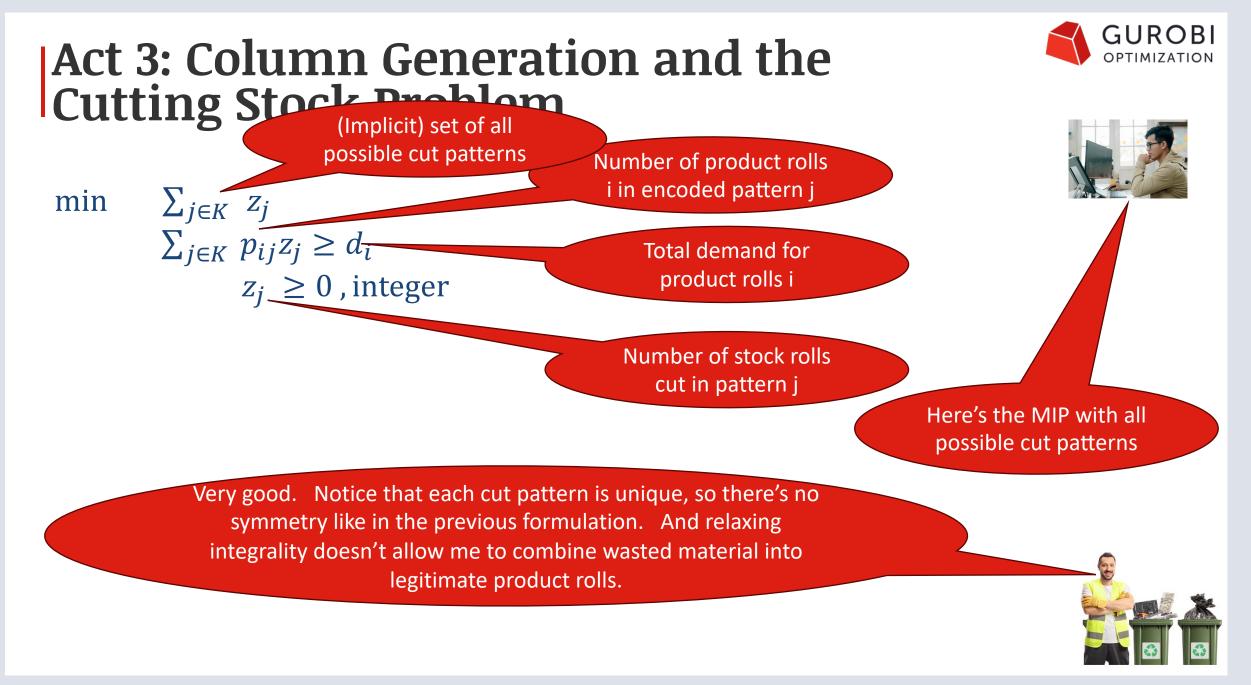
Encoding (5, 0, 0, 0) (0, 3, 0, 0)

(0, 0, 2, 0)

(0, 0, 0, 2)

(1, 0, 2, 0)







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Act 3: Column Generation and the Cutting Stock Problem

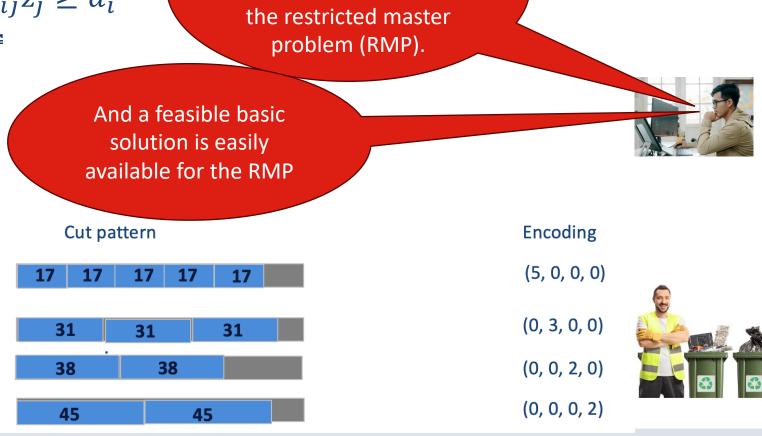
Full master problem:

 $\begin{array}{ll} \min & \sum_{j \in J} \ z_j + \sum_{j \in K/J} z_j \\ y : & \sum_{j \in J} \ p_{ij} z_j + \sum_{j \in K/J} p_{ij} z_j \geq d_i \\ & z_j \ \geq 0 \ \overline{, \text{ integer}} \end{array}$

Now we relax integrality and separate the patterns that go into the restricted master problem (RMP).

Restricted master problem:

 $\begin{array}{ll} \min & \sum_{j \in J} z_j \\ y \colon & \sum_{j \in J} p_{ij} z_j \ge d_i \\ & & z_i \ge 0 \end{array}$





Restricted master problem:

 $\sum_{i \in I} Z_i$ min $\sum_{i \in J} p_{ij} z_j \ge d_i$ *y*: $z_i \geq 0$

Now I just need to automate the thought process I used to find an improving cut pattern

I implicitly used the reduced cost computation $c_i - c_B^T (A_B^{-1} A_i)$, but for the subproblem, the equivalent computation $c_i - (c_B^T A_B^{-1}) A_i$ works better

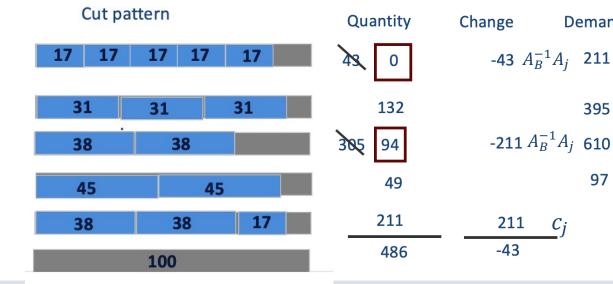
Demand

395

97

 C_i

Subproblem: max $y^T p y^T p$ $\sum_{i=1}^{r} w_i p_i \leq W$ $p \geq 0$, integer







Subproblem: max $y^T p$

 $\sum_{i=1}^{r} w_i p_i \le W$ $p \ge 0, \text{ integer}$

 $p_q, q \in K/J$

Restricted master problem:

min

y:

$$\sum_{j \in J} z_j + z_q$$

$$\sum_{j \in J} p_{ij} z_j + p_{iq} z_q \ge d_i$$

$$z_j, z_q \ge 0$$

The subproblem is an integer program with one variable per product roll. It is a single constraint knapsack problem that's easy to solve

Its optimal solution comes from the implicit cut patterns in the full master problem. If that new pattern has a negative reduced cost, the objective of the restricted master problem will improve.

Full master problem:

min

y:

$$\sum_{j \in J} z_j + \sum_{j \in K/J} z_j$$

$$\sum_{j \in J} p_{ij} z_j + \sum_{j \in K/J} p_{ij} z_j \ge d_i$$

$$z_j \ge 0 \text{,integer}$$





Restricted master problem:

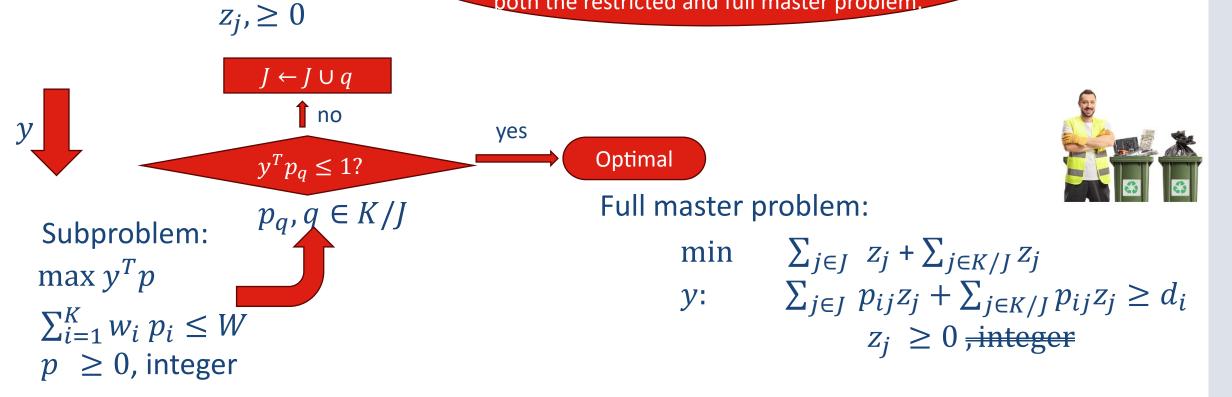
 $\sum_{i \in I} p_{ij} z_j \ge d_i$

 $\sum_{i \in I} Z_i$

min

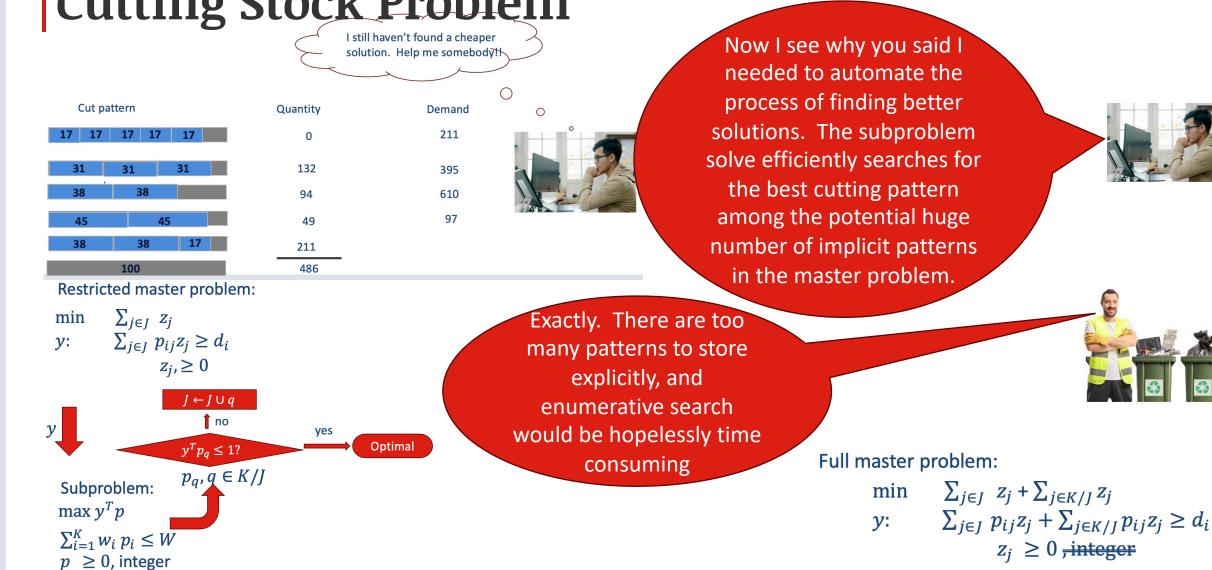
y:

I can repeat this process, and when the best cut pattern no longer has a favorable reduced cost, I have the optimal solution to both the restricted and full master problem.



Act 3: Column Generation and the Cutting Stock Problem



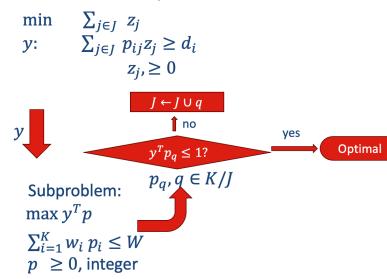


Act 3: Column Generation and the Cutting Stock Problem



But wait a minute. Column generation has solved the full master problem LP. That might have fractional solutions, and I need an integer number for each cut pattern used.

Restricted master problem:



Try solving it and see what you get.

Full master problem:

 $\begin{array}{ll} \min & \sum_{j \in J} \ z_j + \sum_{j \in K/J} z_j \\ y & \sum_{j \in J} \ p_{ij} z_j + \sum_{j \in K/J} p_{ij} z_j \geq d_i \\ & z_j \ \geq 0 \text{ , integer} \end{array}$



Act 3: Column Generation and the Solving the full master LP using column generation

Quantity

0

0

0

43.75

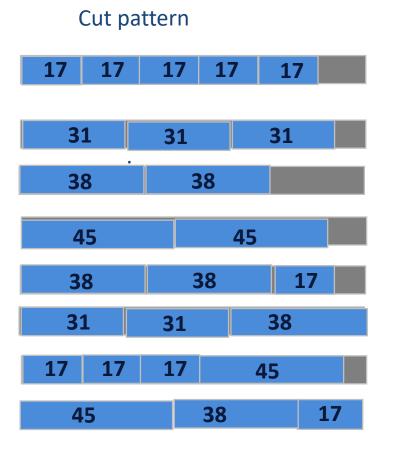
201.5

197.5

0

9.5

452.25



100

using column generation was easy to program using Gurobi's Python API

> Yes, we use Gurobi for our routing problems. You could have programmed using C, C++, C#, Java and other languages as well.

> > In the last 30 years, LP/MIP solver APIs have made the implementation of decomposition algorithms like column generation much easier



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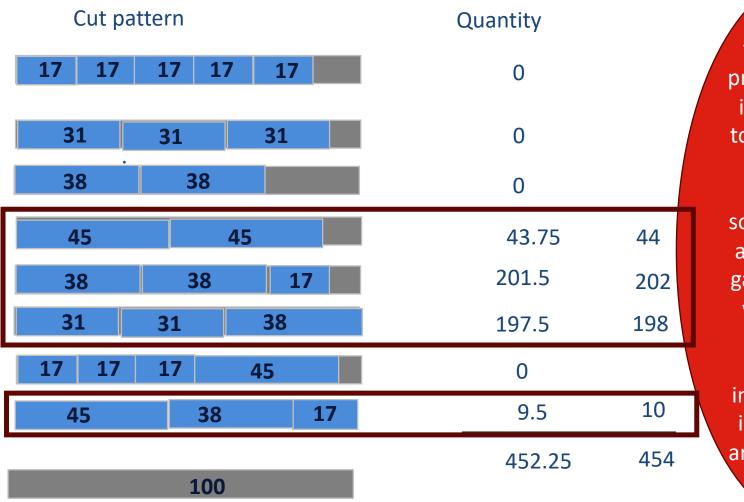


Act 3: Column Generation and the Cutting Stock Problem

Cut pattern 17 17 17 17 17 31 31 31 31 1 38 38 1 1 1	Quantity 0 0 0	fraction satisfies de the inte obtained b	see. Since this hal solution mand, so does ger solution y rounding the al values up.
45 45	43.75	44	
38 38 17	201.5	202	And the optimal
31 31 38	197.5	198	LP objective value rounded up gives you a strong
17 17 17 45	0		
45 38 17	9.5	10	bound on the best possible
100	452.25	454	integer solution.



Act 3: Column Generation and the Cutting Stock Problem



And as long as the number of product roll types is small relative to the number of stock rolls cut, the rounded solution will have a very good MIP gap. In this case, with 4 product roll types, the worst case integer objective is 450 + 4 = 454 and the best case is 453







Intermission

Questions?

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(Longer) Intermission

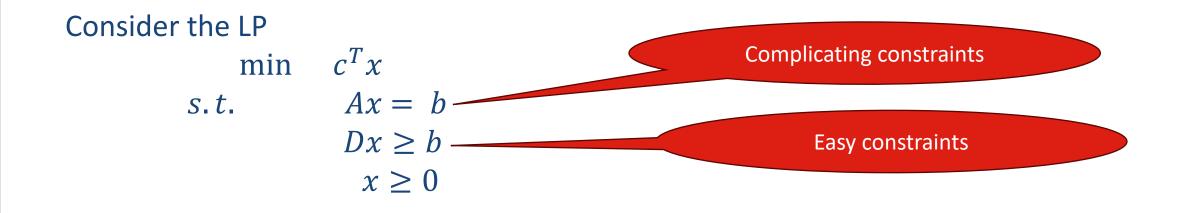
Let p1,...,pj and r1,...,rk be all extreme points and extreme rays of Ax=b, x>=0. Reformulate the LP as A(u1 p1 + ... + uj pj + v1 r1 + ... + vk rk) = b with ui >= 0 and sum uj = 1....



But first, what are the takeaways from Act 3?

- The Column Generation formulation was much larger, but it was stronger than the compact formulation.
- The iterative procedure involving a dialog between the Boss and the Software Engineer that emerged in Acts 1 and 2 now has a corresponding mathematical interpretation involving a "dialog" between the restricted master problem and sub problem. In both cases, information was traded that helped refine the best solution.
- The number of nonzero variables in an optimal basic solution to an LP is bounded by the number of constraints, not the number of variables.



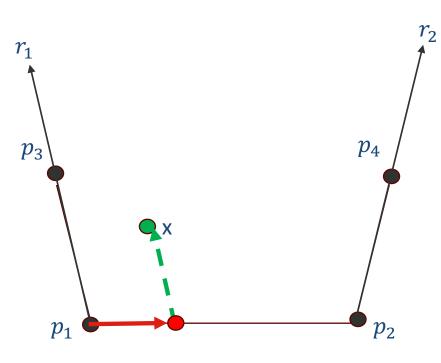


- To simplify the discussion, assume the feasible regions associated with the easy and complicating constraints are both bounded.
 - This just simplifies the math; it does not fundamentally alter the algorithmic computations.



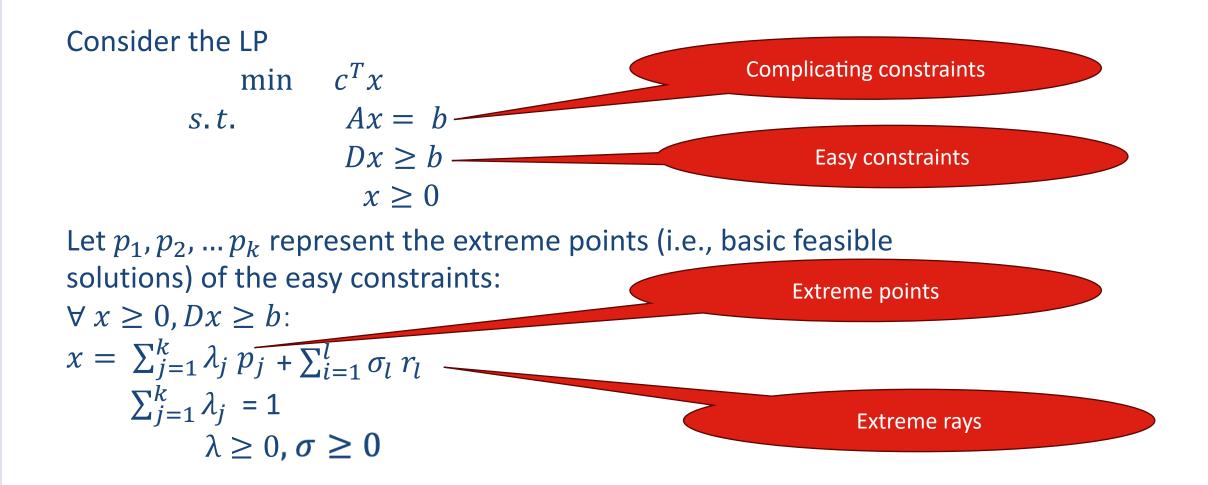
Extreme points and extreme rays

 Any point in a polyhedron (feasible region of an LP) can be represented as a convex combination of extreme points and nonnegative linear combination of extreme rays.



Let $p_1, p_2, ..., p_k$ represent the extreme points (i.e., basic feasible solutions) of the easy constraints: $\forall x \ge 0, Dx \ge b$: $x = \sum_{j=1}^k \lambda_j p_j + \sum_{i=1}^l \sigma_l r_l$ $\sum_{j=1}^k \lambda_j = 1$ $\lambda \ge 0, \sigma \ge 0$





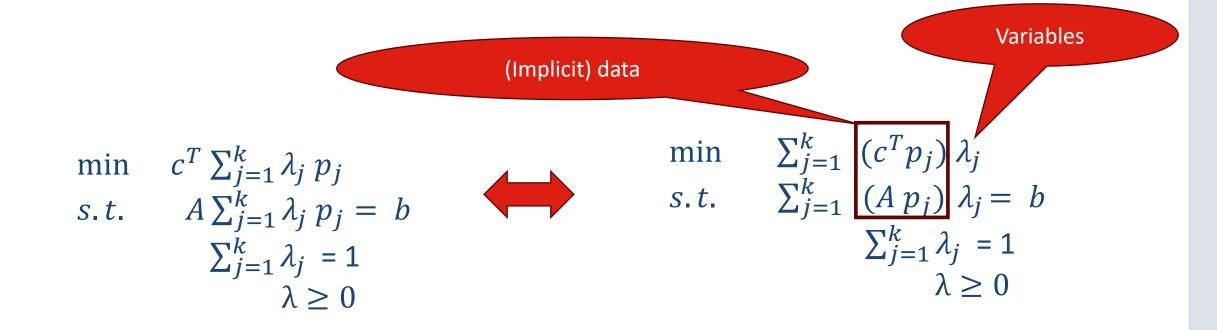


k can be huge, but let's substitute the extreme point representation of the easy constraints into our original formulation.

$$\forall x \ge 0, Dx \ge b: x = \sum_{j=1}^{k} \lambda_j p_j \sum_{j=1}^{k} \lambda_j = 1 \lambda \ge 0$$

 $\begin{array}{cccc} \min & c^{T}x & \min & c^{T}\sum_{j=1}^{k}\lambda_{j} p_{j} \\ s.t. & Ax = b & \\ & Dx \ge b & \\ & x \ge 0 & & & \\ & & & \sum_{j=1}^{k}\lambda_{j} = 1 \\ & & & & \lambda \ge 0 \end{array}$

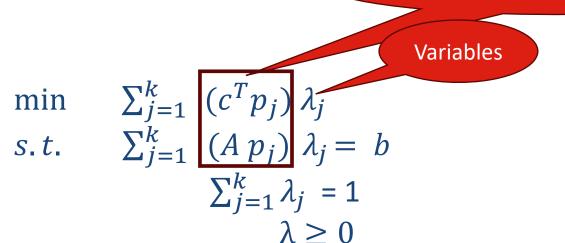








Master problem



Suppose A₂ has 10000 constraints and 10³⁰ variables. At any simplex method iteration, how many variables are basic? A) < 10000 B) 10000 C) More than 10000 but less than 10³⁰ D) 10³⁰

The master problem has a potentially huge number of variables. But as long as the number of constraints is modest, the number of variables in an optimal basic solution is modest. Can we avoid explicitly representing all the variables in the master problem?

(Implicit) data



Can we avoid explicitly representing all the variables in the master problem?

Let $J \subset K = \{1, ..., k\}$ be a small subset of the extreme points of the easy constraints

Restricted Master Problem:



$$\sum_{j \in J} (c^{T} p_{j}) \lambda_{j}$$

$$\sum_{j \in J} (A p_{j}) \lambda_{j} = b$$

$$\sum_{j \in J} \lambda_{j} = 1$$

$$\lambda \ge 0$$

Wait a minute. How do I know this problem isn't so restricted that it's infeasible?

You don't. But in many cases a small collection of extreme points that is feasible can be easily constructed.





Can we avoid explicitly representing all the variables in the master problem?

Cut pattern

17

38

45

17 17

38

100

45

31

17

31

Let $J \subset \{1, ..., k\}$ be a small subset of the extreme points of the easy constraints **Restricted Master Problem:**

min $\sum_{j \in J} (c^T p_j) \lambda_j$ s.t. $\sum_{j \in J} (A p_j) \lambda_j = b$

Remember how easily you constructed your first solution to the cutting stock problem? It wasn't that cost efficient, but it was feasible



Oursetitus	
Quantity	Demand
43	211
132	395
305	610
49	97
529	



Can we avoid explicitly representing all the variables in the master problem?

h

Let $J \subset \{1, ..., k\}$ be a small subset of the extreme points of the easy constraints Restricted Master Problem:

min s.t.

$$\sum_{\substack{j \in J \\ j \in J \\ j \in J \\ \sum_{j \in J} \lambda_j = 1 \\ \lambda > 0} (c^T p_j) \lambda_j = 1$$

But even if you can't do that, you can add a single auxiliary column to address the shortfalls or excesses associated with the variables in the restricted master problem





Can we avoid explicitly representing all the variables in the master problem?

Let $J \subset \{1, ..., k\}$ be a small subset of the extreme points of the easy constraints Restricted Master Problem (RMP):

min *s.t*.

 $\sum_{\substack{j \in J \\ j \in J \\ \sum_{j \in J} \lambda_j = 1}} (c^T p_j) \lambda_j$

OK, so after I have solved the RMP, what do I do next?



Think Column Generation and the first pass you made with the cutting stock problem. You looked at patterns that appeared to be wasteful and tried to replace them with less wasteful ones that would reduce the overall cost. An optimal basic solution provides reduced costs that you can use to automate what you did manually.



Standard form LP

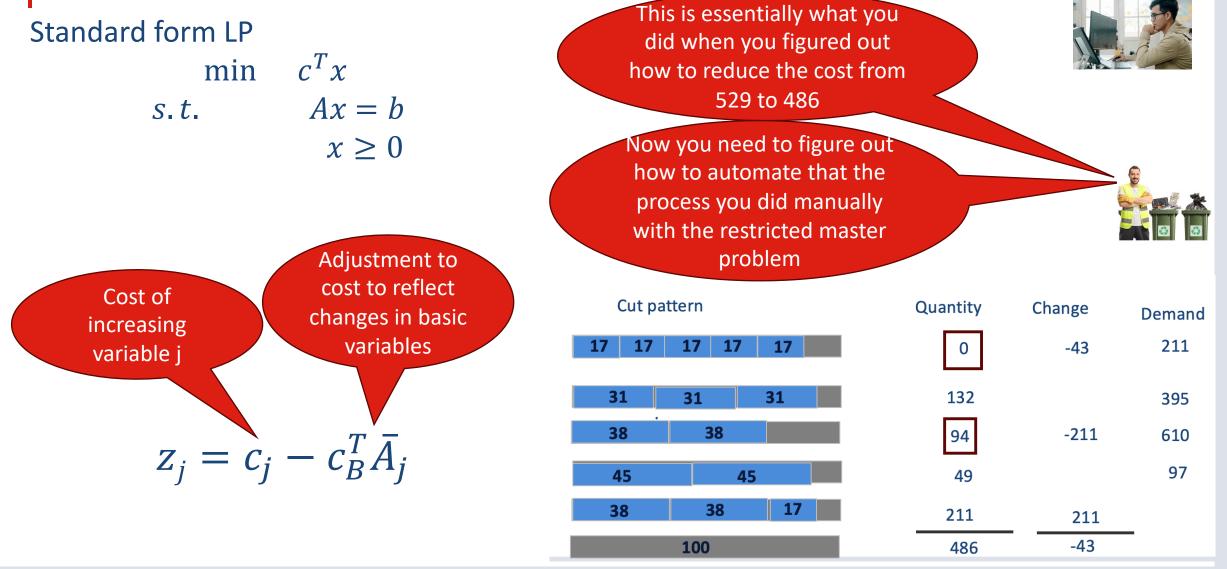
$$\begin{array}{ll} \min & c^T x\\ s.t. & Ax = b\\ & x \ge 0 \end{array}$$

$$A = (A_B, A_N)$$

$$\bar{c}_j = c_j - c_B^T A_B^{-1} A_j = c_j - (c_B^T A_B^{-1}) A_j = c_j - c_B^T (A_B^{-1} A_j)$$

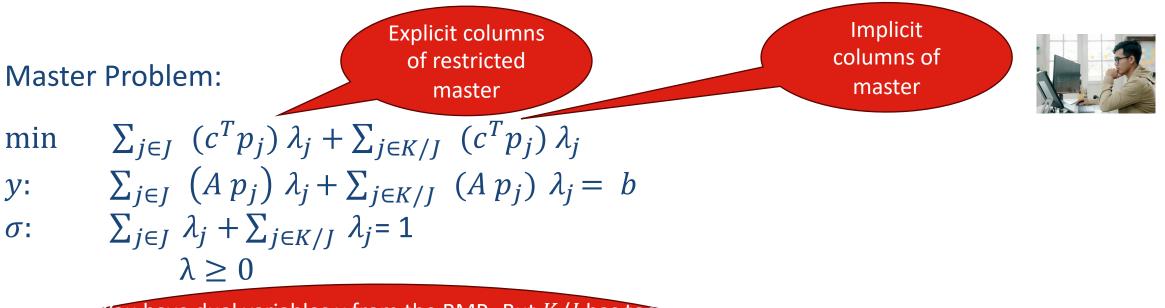






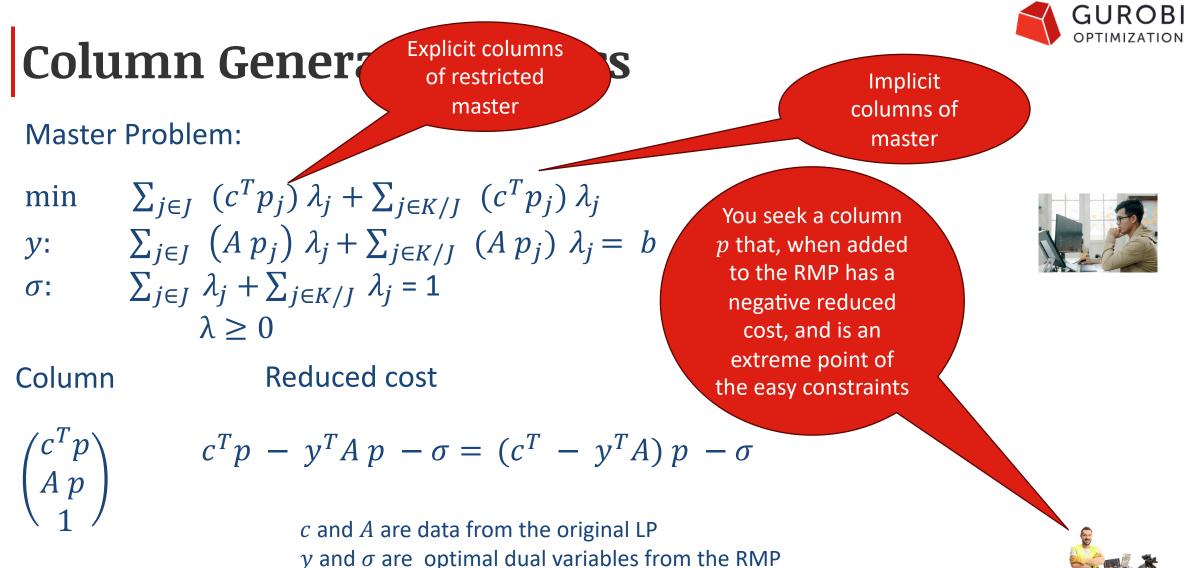


Let $J \subset K = \{1, ..., k\}$ be a small subset of the extreme points of the easy constraints



You have dual variables y from the RMP. But K/J has too many columns (extreme points) to compute all the reduced costs explicitly to find the one that reduces the overall cost the at the highest rate. But you can use the first reduced cost formula $z_j = c_j - y^T A_j$ to create a subproblem to efficiently find the most negative reduced cost.



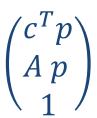


y and σ are optimal dual variables from the RIVIP p is a vector of decision variables with dimension equal to the number of variables in the original LP



Column

Reduced cost



$$c^T p - y^T A p - \sigma = (c^T - y^T A) p - \sigma$$

Sub Problem:

 $\min(c^T - y^T A) p$ s.t. $Dp \ge b$ $p \ge 0$ You figured out decision variables *p* yourself when you reduced the cost from 529 to 486. But you can automate this calculation by solving this subproblem instead.

c and A are data from the original LP y and σ are optimal dual variables from the RMP p is a vector of decision variables with dimension equal to the number of variables in the original LP





Let p^* be an optimal solution to the Sub Problem:

 $\min(c^T - y^T A) p$ s.t. $Dp \ge b$ $p \ge 0$

If $c^T p^* - y^T A p^* - \sigma < 0$, then p^* is an extreme point of the easy constraints that can be added to the RMP. Reoptimize the RMP with the added column and do another column generation iteration.

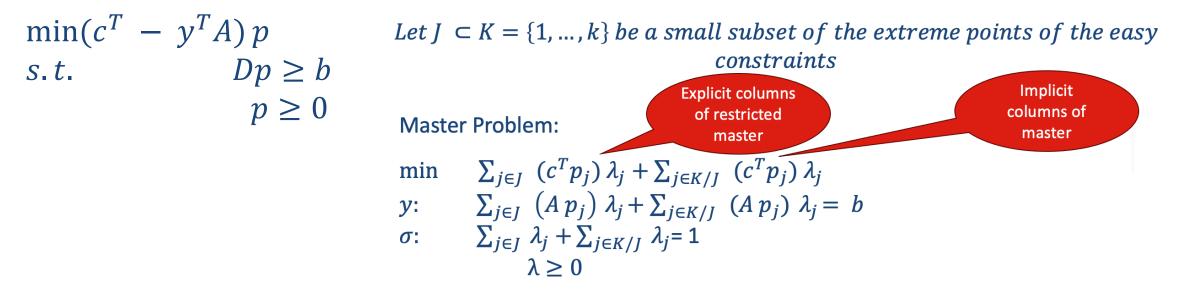






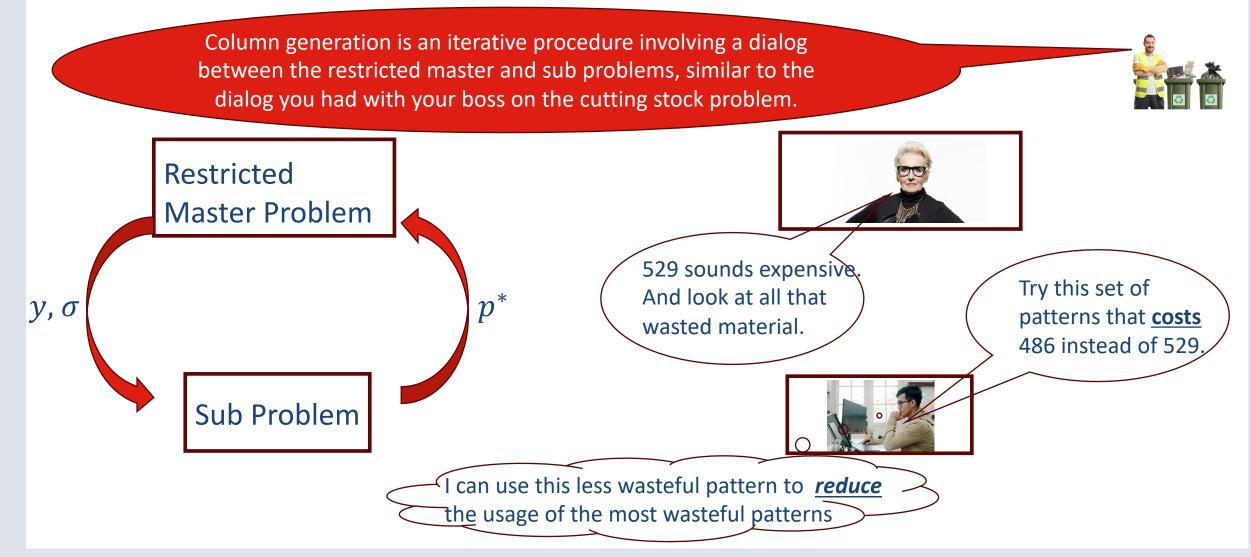


Let p^* be an optimal solution to the Sub Problem:



If $c^T p^* - y^T A p^* - \sigma \ge 0$, the Sub Problem solve proves that all implicit columns of the full master problem have even larger reduced costs, proving optimality of the full master problem in addition to the restricted master. The column generation algorithm terminates.



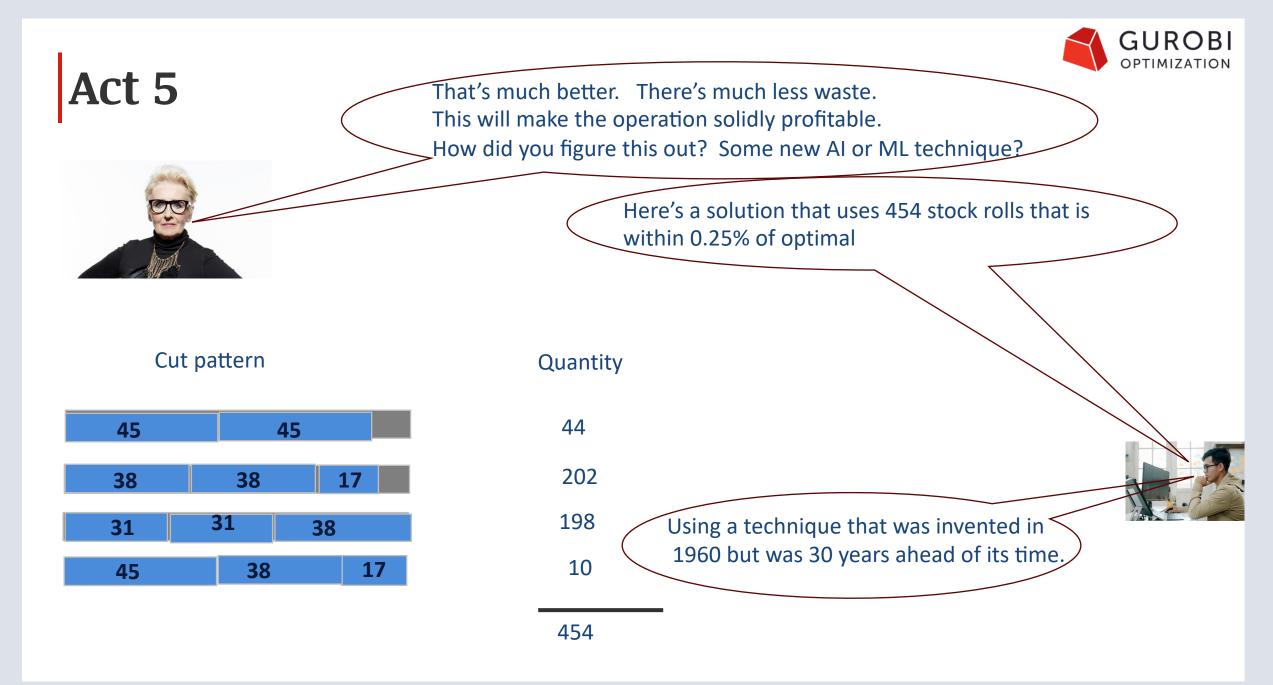




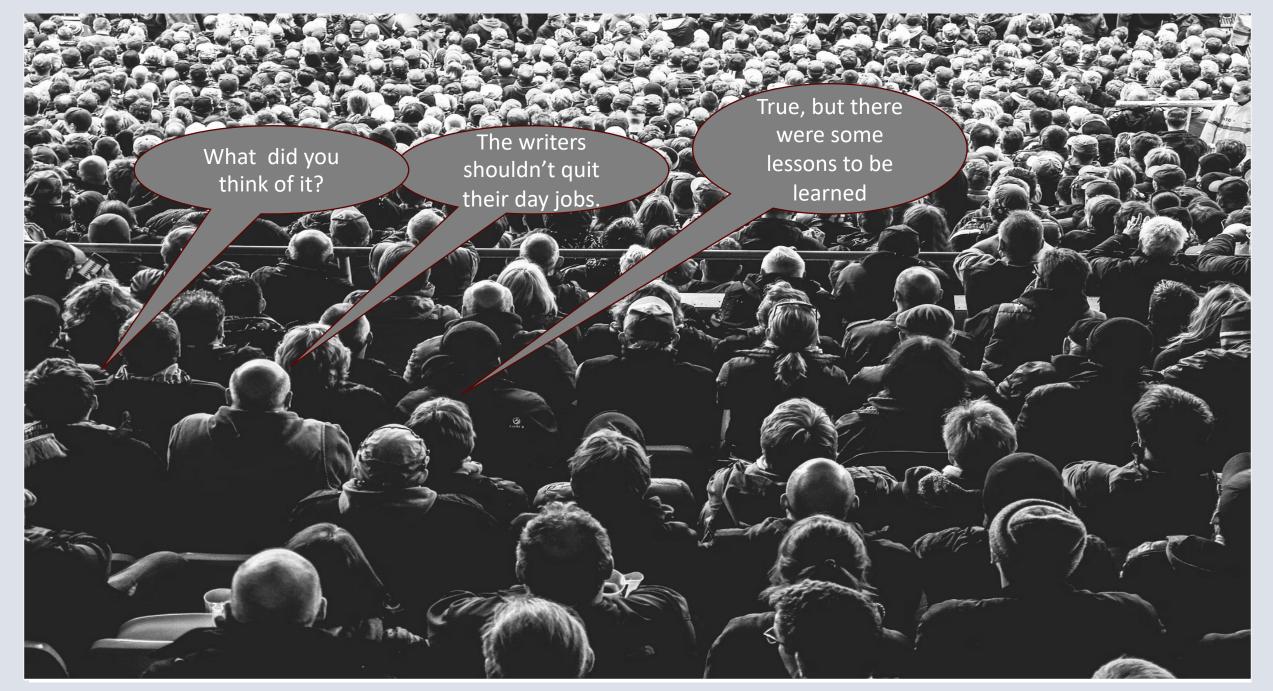
Intermission

Questions?

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Takeaways

- Column Generation is more mathematically complex and counterintuitive than LP and MIP algorithms, but the models are more intuitive for those with little or no exposure to mathematical programming
- May need to choose between compact but weak MIP vs huge but strong MIP
- LPs and MIPs with too many variables to represent explicitly but modest number of constraints may still be solvable
 - Let the subproblem determine which variables appear in an optimal basis
 - The same is true for too many constraints but modest number of variables; Benders' decomposition is Dantzig-Wolfe decomposition applied to the dual LP
- Today's solver APIs make Dantzig-Wolfe and similar decomposition methods straightforward to implement
 - However, unlike a generic MIP or LP solver, they must be customized to the individual model
 - Try the generic MIP or LP solver first, even on a weaker formulation



Thank You

For more information: gurobi.com



Additional Resources

 Marco E. Lübbecke, Jacques Desrosiers, (2005) Selected Topics in Column Generation. Operations Research 53(6):1007-1023. https://doi.org/10.1287/opre.1050.0234

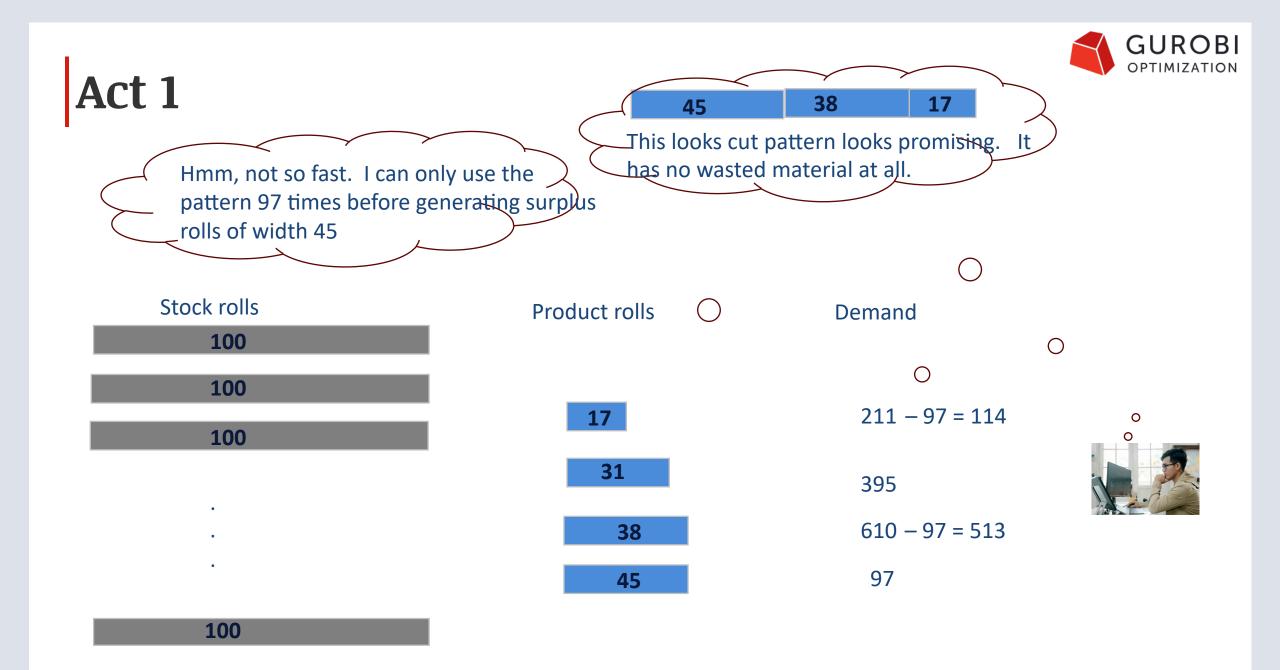


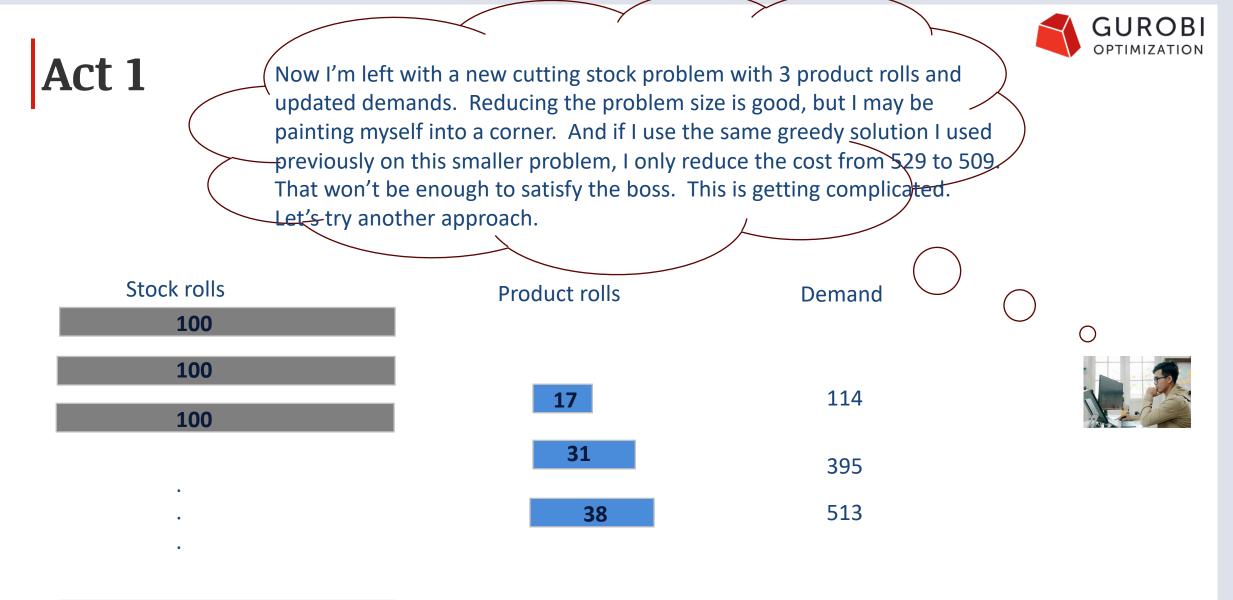
- Marco E. Lübbecke, Column Generation, Dantzig-Wolfe, Branch-Priceand-Cut. Video from CO@Work, 2020. <u>https://www.youtube.com/watch?v=vx2LNKx48vY</u>
- 3. Sergiy Butenko, Column Generation for the Cutting Stock Problem <u>https://www.youtube.com/watch?v=O918V86Grhc</u>
- 4. Sergiy Butenko, Dantzig-Wolfe Decomposition: Intro https://www.youtube.com/watch?v=IposxYVBUnY&t=891s
- 5. Video of an industrial strength paper cutting machine: <u>https://www.youtube.com/watch?v=0zF6PWr7W8Y</u>
- 6. Cutting stock (and other tech talk models) programs: https://github.com/Gurobi/techtalks/tree/main/mipformulations/programs/



Backup

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Question 4

Consider the LP min $c^T x$ s.t. $A_3 x = b$ $x \ge 0$

Suppose A_3 has 10000 constraints and 10³⁰ variables. How many different bases are there?

A) 10000

B) 10³⁰!/10000!(10³⁰ - 10000)!

C) 10³⁰

D) Too many



Question 2

Consider the LP min $c^T x$ s.t. $A_2 x = b$ $x \ge 0$

Suppose A₂ has 10000 constraints and 1000000 variables. At any simplex method iteration, how many variables are basic?

- A) <10000
- B) 10000
- C) More than 10000 but less than 1000000
- D) 100000